Implementing finite state machines in Verilog

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Introduction

Objectives:

Describing the finite state machines in Verilog

For reading:

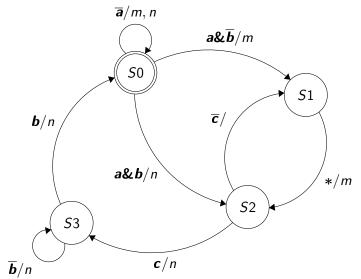
 Chris Fletcher: "EECS150: Finite State Machines in Verilog", [Flet08]

This material will present a method for behavioural description of Mealy type *finite state machines* using Verilog. The method can be readily adapted for Moore type FSM.

The Verilog behavioural description aim to use the synthesizable set of the HDL, facilitating direct implementation using the synthesis tools used for digital design.

Case study

Implementing a Mealy machine described by transition diagram *Exercise*: Implement the following FSM:



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Case study (contd.)

Implementing a Mealy machine described by transition diagram

By *analyzing* the transition diagram, the following observations can be made:

- the machine has 3, 1-bit inputs: *a*, *b* si *c*
- at the output, the automaton can activatre any of its 2, 1-bit outputs: *m* si *n*
- the machine can be in any of its 4 states: S0, S1, S2 sau S3
- state *S0* is the initial state (activated after device's initialization)

A transition between two states of the machine is symbolized by an arc, labeled with the logic condition taht triggers the respective transition, together with the activated outputs.

The format of the arc's label is : logic_condition/activated_output, ...

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The five steps of implementing finite state machines $_{\mbox{\scriptsize Step 1}}$

Define named constants for each state of the machine. The constants are declared using localparam keyword. Each state constant has a distinct value, represented on the necessary number of bits (for a machine with 13 states, the state constants' values are represented on 4 bits)

For the proposed exercise, the state constants are defined as in the following code fragment:

- 1 localparam $S0_ST = 2'd0;$
- $_2$ localparam S1_ST = 2'd1;
- 3 localparam S2_ST = 2'd2;
- 4 localparam $S3_ST = 2'd3;$

Recommendation: The name of the four state constants should include the _ST suffix.

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The five steps of implementing finite state machines $_{\mbox{\scriptsize Step 2}}$

Define the current state and the next state signals. The current state signal, *st*, is assigned values in an always block, thus being defined with the reg specifier, on the same number of bits as the values of the state constants.

The next state signal, st_nxt , has the same number of bits as st, and is generated by a combinational logic, dependent on the current state, st, and the finite state machine's inputs. However, if st_nxt is assigned values in an always block, it will be declared with reg specifier.

For the current exercise, the two signals are defined as follows:

```
1 reg [1:0] st;
2 reg [1:0] st_nxt;
```

The five steps of implementing finite state machines $_{\mbox{\scriptsize Step 3}}$

The next state is generated based on the transition diagram, in an combinational always block. One can use the case(st) instruction for handling the transitions associated with each state:

```
always @ (*)
1
            case(st)
2
                     SO_ST: if (!a) st_nxt = SO_ST;
3
                                 else if (b) st_nxt = S2_ST;
4
                                 else st_nxt = S1_ST;
5
                     S1_ST: st_nxt = S2_ST:
6
                     S2_ST: if (c) st_nxt = S3_ST;
7
                                 else st_nxt = S1_ST;
8
                     S3_ST: if (b) st_n \times t = S0_ST;
9
                                 else st_nxt = S3_ST;
10
            endcase
11
```

Important: The implementation must assure that all possible input configurations, for each state, are covered by the if ... else instructions (no input configuration is left without being handled by the Verilog code). © 2023 Opritoid Flavius. All Rights Reserved.

The five steps of implementing finite state machines $_{\mbox{\scriptsize Step 4}}$

The output of the finite state machine are constructed from the transition diagram, using a combinational always block. using the case(st) instruction, the outputs associated with each state transition are activated:

```
always @ (*) begin
1
          m = 1'd0;
2
            n = 1' d0;
3
            case(st)
4
                     SO_ST: if (!a) \{m, n\} = 2'b11;
5
                                 else if (b) n = 1'd1;
6
                                 else m = 1'd1;
7
                     S1_ST: m = 1'd1:
8
                     S2_ST: if (c) n = 1'd1;
9
                     S3_ST: n = 1'd1;
10
            endcase end
11
```

Important: For avoiding setting outputs to their default values on branches (such as on the *else* branch of instruction in line 9), all outputs are first initialized to their default value (lines 2 and 3). © 2023 Opritoiu Flavius. All Rights Reserved.

The five steps of implementing finite state machines $_{\mbox{\scriptsize Step 5}}$

The current state is updated in a sequential always block. At each triggering edge of the clock, the current state takes the value of the next state signal. If the finite state machine has an asynchronous reset line, it is to be checked for activation.

With small adaptations, the code fragment bellow can be used for updating the current state for any finite state machine:

```
1 always @ (posedge clk, negedge rst_b)
2 if (!rst_b) st <= S0_ST;
3 else st <= st_nxt;</pre>
```

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Complete Verilog implementation

```
1
     module fsm (
 2
              input clk. rst_b.
3
4
5
6
7
8
9
              input a, b, c,
              output reg m. n
     ):
              localparam S0_ST = 2'd0:
              localparam S1_ST = 2'd1;
              localparam S2_ST = 2'd2:
              localparam S3_{*}ST = 2'd3:
10
              reg [1:0] st;
11
              reg [1:0] st_nxt;
12
              always @ (*)
13
                       case(st)
14
                                SO_ST: if (!a) st_nxt = SO_ST;
15
                                                  else if (b) st_nxt = S2_sT:
16
                                                  else st_nxt = S1_ST;
17
                                S1_ST: st_nxt = S2_ST:
18
                                S2_ST: if (c) st_nxt = S3_ST:
19
                                                  else st_nxt = S1_ST;
20
                                S3_ST: if (b) st_n xt = S0_ST;
21
22
                                                  else st_nxt = S3_{-}ST:
                       endcase
23
              always @ (+) begin
24
                       m = 1'd0:
25
26
27
                       n = 1' d0;
                       case(st)
                                S0_ST: if (!a) \{m, n\} = 2'b11:
28
29
                                                  else if (b) n = 1'd1;
                                                  else m = 1'd1:
30
31
                                S1.ST: m = 1'd1;
                                S2_ST: if (c) n = 1'd1:
32
33
34
35
                                S3 ST :
                                        n = 1'd1:
                       endcase end
              always @ (posedge clk, negedge rst_b)
                       if (! rst_b) st \leq S0_ST:
36
                       else st <= st_nxt:
37
     endmodule
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```

References

[Flet08] C. Fletcher. EECS150: Finite State Machines in Verilog. [Online]. Available: http: //inst.eecs.berkeley.edu/~cs150/fa08/Documents/FSM.pdf (Last accessed 25/04/2016).